



**Weierstrass Institute for
Applied Analysis and Stochastics**



Simulation of conditional diffusions via forward-reverse stochastic representations

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- 3 A forward-reverse representation for conditional expectations**
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1 Introduction

2 The forward-reverse method for transition density estimation

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4 The forward-reverse estimator

5 Numerical examples

6 Applications to the EM algorithm

Given $a : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, $\sigma : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^{d \times m}$, a standard, m -dimensional Brownian motion B , consider

$$dX(s) = a(s, X(s))ds + \sigma(s, X(s))dB(s), \quad 0 \leq s \leq T$$

Goal

Given a grid $\mathcal{D} = \{0 = s_0 < \dots < s_{K+L+1} = T\}$, $f : \mathbb{R}^{(K+L)d} \rightarrow \mathbb{R}$ and $x, y \in \mathbb{R}^d$, compute

$$\mathbb{E}[f(X(s_1), \dots, X(s_{K+L})) \mid X(0) = x, X(T) = y].$$

Given $a : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, $\sigma : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^{d \times m}$, a standard, m -dimensional Brownian motion B , consider

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Goal (extended)

Given a grid $\mathcal{D} = \{0 = s_0 < \dots < s_{K+L+1} = T\}$, $f : \mathbb{R}^{(K+L)d} \rightarrow \mathbb{R}$ and $A \subset \mathbb{R}^d$, compute

$$\mathbb{E}[f(X(s_1), \dots, X(s_{K+L})) \mid X(0) = x, X(T) \in A],$$

A with positive measure or d' -dimensional hyperplanes, $0 \leq d' \leq d$.

Given $a : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, $\sigma : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^{d \times m}$, a standard, m -dimensional Brownian motion B , consider

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$$\mathbb{E}[f(X(s_1), \dots, X(s_{K+L})) \mid X(0) = x, X(T) = y].$$

Extension

- ▶ Discrete time Markov chains [B., Mai, Schoenmakers]
- ▶ Pure jump Markov process [B., Moraes, Villanova, Tempone]

- ▶ Algorithm for maximizing likelihood with missing data

Example: Two-stage hierarchical model:

- ▶ Random variables Y and U (multi-variate)
- ▶ $U \sim h(\cdot; \theta)$, $Y|U = u \sim f(\cdot|u; \theta)$, $\theta \in \Theta$
- ▶ Data: y (instance of Y), but U not observable

Algorithm

Let $l(\theta; y) := \log \int f(y|u; \theta)h(u; \theta)du$, $\hat{\theta} := \arg \max_{\theta \in \Theta} l(\theta; y)$. Given θ_0 .

(E) $Q(\theta|\theta_n, y) := E_{\theta_n} [\log (f(y|U, \theta)h(U; \theta)) | Y = y]$

(M) $\theta_{n+1} := \arg \max_{\theta \in \Theta} Q(\theta|\theta_n, y)$.

- ▶ $l(\theta_{n+1}; y) \geq l(\theta_n; y)$
- ▶ Weak conditions: $\theta_n \rightarrow \theta^*$ with $\nabla l(\theta^*; y) = 0$

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- ▶ OU-process: $dX_s = -\theta X_s ds + dW_s$, $s \in [0, T]$
- ▶ On path space:

$$L_c(X; \theta) = \frac{dP^\theta}{dP^0}(X) = \exp\left(-\theta \int_0^T X_s dX_s - \frac{\theta^2}{2} \int_0^T X_s^2 ds\right)$$

- ▶ Discrete observations: $\mathbf{x} = (x_0, \dots, x_K)$ of $\mathbf{X} := (X(s_0), \dots, X(s_K))$,
 $s_0 = 0, s_K = T$
- ▶ EM algorithm with

$$\begin{aligned} Q(\theta|\theta_n, \mathbf{x}) &= \mathbb{E}_{\theta_n} \left[-\theta \int_0^T X_s dX_s - \frac{\theta^2}{2} \int_0^T X_s^2 ds \mid \mathbf{X} = \mathbf{x} \right] \\ &= \sum_{i=1}^K \mathbb{E}_{\theta_n} \left[-\theta \int_{s_{i-1}}^{s_i} X_s dX_s - \frac{\theta^2}{2} \int_{s_{i-1}}^{s_i} X_s^2 ds \mid X_{s_{i-1}} = x_{i-1}, X_{s_i} = x_i \right] \end{aligned}$$

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- ▶ Notation: $X_{t,x}(s)$ solution of SDE started at $X_{t,x}(t) = x$, $t < s$
- ▶ Generator of the SDE:

$$L_t f(x) = \langle \nabla f(x), a(t, x) \rangle + \frac{1}{2} \sum_{i,j=1}^d b^{ij}(t, x) \partial_{x^i} \partial_{x^j} f(x),$$

where $b^{ij}(t, x) = \sigma(t, x)\sigma(t, x)^T$

- ▶ Transition density $p(t, x, T, y)$

Forward representation (Feynman Kac formula)

$$u(t, x) = \mathbb{E} [f(X_{t,x}(T))] = \int p(t, x, T, y) f(y) dy =: I(f)$$

$$\partial_t u(t, x) + L_t u(t, x) = 0, \quad u(T, x) = f(x)$$

- ▶ Consider: $v(s, y) := \int g(x)p(t, x, s, y)dx$

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Fokker-Planck equation:

$$\partial_s p(t, x, s, y) = \frac{1}{2} \sum_{i,j=1}^d \partial_{y^i} \partial_{y^j} (b^{ij}(s, y)p(t, x, s, y)) - \sum_{i=1}^d \partial_{y^i} (a^i(s, y)p(t, x, s, y))$$

- ▶ Consider: $v(s, y) := \int g(x)p(t, x, s, y)dx$

Cauchy problem for v

$$\partial_s v(s, y) = \frac{1}{2} \sum_{i,j=1}^d \partial_{y^i} \partial_{y^j} (b^{ij}(s, y)v(s, y)) - \sum_{i=1}^d \partial_{y^i} (a^i(s, y)v(s, y)),$$
$$v(t, y) = g(y)$$

- ▶ Consider: $v(s, y) := \int g(x)p(t, x, s, y)dx$

Cauchy problem for $\tilde{v}(s, y) := v(T + t - s, y)$

$$\partial_s \tilde{v}(s, y) + \frac{1}{2} \sum_{i,j=1}^d \tilde{b}^{ij}(s, y) \partial_{y^i} \partial_{y^j} \tilde{v}(s, y) + \sum_{i=1}^d \alpha^i(s, y) \partial_{y^i} \tilde{v}(s, y) + c(y) \tilde{v}(s, y) = 0,$$

$$\tilde{v}(T, y) = g(y),$$

where $\tilde{b}(s, y) := b(T + t - s, y)$, $\tilde{a}(s, y) := a(T + t - s, y)$,

$$\alpha^i(s, y) := \sum_{j=1}^d \partial_{y^j} \tilde{b}^{ij}(s, y) - \tilde{a}^i(s, y),$$

$$c(s, y) = \frac{1}{2} \sum_{i,j=1}^d \partial_{y^i} \partial_{y^j} \tilde{b}^{ij}(s, y) - \sum_{i=1}^d \partial_{y^i} \tilde{a}^i(s, y)$$

- ▶ Consider: $v(s, y) := \int g(x)p(t, x, s, y)dx$

Reverse representation (Feynman-Kac formula)

$$I^*(g) := v(T, y) = \mathbb{E} [g(Y(T)) \mathcal{Y}(T)]$$

$$dY(s) = \alpha(s, Y(s))ds + \tilde{\sigma}(s, Y(s))dB(s), \quad Y(t) = y,$$

$$d\mathcal{Y}(s) = c(s, Y(s))\mathcal{Y}(s)ds, \quad \mathcal{Y}(t) = 1$$

$$\alpha^i(s, y) := \sum_{j=1}^d \partial_{y^j} \tilde{b}^{ij}(s, y) - \tilde{a}^i(s, y),$$

$$c(s, y) = \frac{1}{2} \sum_{i,j=1}^d \partial_{y^i} \partial_{y^j} \tilde{b}^{ij}(s, y) - \sum_{i=1}^d \partial_{y^i} \tilde{a}^i(s, y)$$

Theorem (Milstein, Schoenmakers, Spokoiny 2004)

Choose X and (Y, \mathcal{Y}) independent, $t < t^* < T$:

$$\begin{aligned}\mathbb{E} \left[f \left(X_{t,x}(t^*), Y_{t^*,y}(T) \right) \mathcal{Y}_{t^*,y}(T) \right] &= \\ &= \int p(t, x, t^*, x') f(x', y') p(t^*, y', T, y) dx' dy' =: J(f).\end{aligned}$$

- ▶ Formally inserting $f(x', y') = \delta_0(x' - y')$ gives $J(f) = p(t, x, T, y)$
- ▶ Use kernel $f(x', y') = K_\delta(x' - y') := \delta^{-d} K\left(\frac{x' - y'}{\delta}\right)$ with bandwidth $\delta > 0$

Monte Carlo estimator

$$\hat{p}_{N,M,\delta} := \frac{1}{\delta^d MN} \sum_{n=1}^N \sum_{m=1}^M \mathcal{Y}_{t^*,y}^m(T) K\left(\frac{X_{t,x}^n(t^*) - Y_{t^*,y}^m(T)}{\delta}\right)$$

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- ▶ Consider a grid $0 = s_0 < \dots < s_{K+L} = T$
- ▶ Choose $t^* := s_K$, rename $t_i := s_{i+K}$, $\hat{t}_i := T + t^* - t_{L-i}$, $0 \leq i \leq L$
- ▶ Assume $p(s_0, x, T, y) > 0$
- ▶ $K : \mathbb{R}^d \rightarrow \mathbb{R}$, $\int K(u) du = 1$

Theorem

Let $\hat{t}_i := T + t^* - t_{L-i}$, $X_t = X_{s_0, x}(t)$, $Y_t = Y_{t^*, y}(t)$, $\mathcal{Y}_t = \mathcal{Y}_{t^*, y}(t)$, X and (Y, \mathcal{Y}) independent, then

$$\mathbb{E} \left[g(X_{s_1}, \dots, X_{s_{K+L-1}}) \mid X_T = y \right] = \frac{1}{p(s_0, x, T, y)} \lim_{\delta \downarrow 0} \mathbb{E} \left[g(X_{s_1}, \dots, X_{t^*}, Y_{\hat{t}_{L-1}}, \dots, Y_{\hat{t}_1}) K_\delta(Y_T - X_{t^*}) \mathcal{Y}_T \right].$$

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$$\mathbb{E} \left[g(X_{s_1}, \dots, X_{s_{K+L-1}}) \mid X_T = y \right] = \lim_{\delta \downarrow 0} \frac{\mathbb{E} \left[g(X_{s_1}, \dots, X_{t^*}, Y_{\hat{t}_{L-1}}, \dots, Y_{\hat{t}_1}) K_\delta(Y_T - X_{t^*}) \mathcal{Y}_T \right]}{\mathbb{E} \left[K_\delta(Y_T - X_{t^*}) \mathcal{Y}_T \right]}.$$

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Conditions on the diffusion process:

Transition densities $p(s, x, t, y)$ and $q(s, x, t, y)$ of X and Y exist and

$$\left| \partial_x^\alpha \partial_y^\beta p(s, x, t, y) \right| \leq \frac{C_1}{(t-s)^\nu} \exp\left(-C_2 \frac{|y-x|^2}{t-s}\right)$$

for multi-indices $|\alpha| + |\beta| \leq r + 1$ (and sim. for q). Moreover, $p(s_0, x, T, y) > 0$.

Conditions on the kernel:

- ▶ $\int K(v)dv = 1, \int v^\alpha K(v)dv = 0, 0 < |\alpha| \leq r$ (order r kernel)
- ▶ $K(v) \leq C \exp(-\alpha|v|^{2+\beta}), C, \alpha, \beta \geq 0, v \in \mathbb{R}^d$

Conditions on the function:

- ▶ g and its first and second derivatives are polynomially bounded

- ▶ Stochastic representation:

$$H := \mathbb{E} \left[g(X_{s_1}, \dots, X_{t_{L-1}}) \mid X_T = y \right] =$$
$$\lim_{\delta \downarrow 0} \mathbb{E} \left[g(X_{s_1}, \dots, X_{t^*}, Y_{\hat{t}_{L-1}}, \dots, Y_{\hat{t}_1}) K_\delta(Y_T - X_{t^*}) \mathcal{Y}_T \right] / p(s_0, x, T, y)$$

- ▶ Stochastic representation:

$$H := \mathbb{E} \left[g(X_{s_1}, \dots, X_{t_{L-1}}) \mid X_T = y \right] = \lim_{\delta \downarrow 0} \mathbb{E} \left[g(X_{s_1}, \dots, X_{t^*}, Y_{\hat{t}_{L-1}}, \dots, Y_{\hat{t}_1}) K_\delta(Y_T - X_{t^*}) \mathcal{Y}_T \right] / p(s_0, x, T, y)$$

- ▶ Estimator: for (X^n) i.i.d., (Y^m, \mathcal{Y}^m) i.i.d.,

$$\widehat{H}_{\delta, M, N} := \frac{\sum_{n=1}^N \sum_{m=1}^M g \left(X_{s_1}^n, \dots, X_{s_K}^n, Y_{\hat{t}_{L-1}}^m, \dots, Y_{\hat{t}_1}^m \right) K \left(\frac{Y_T^m - X_{t^*}^n}{\delta} \right) \mathcal{Y}_T^m}{\sum_{n=1}^N \sum_{m=1}^M K \left(\frac{Y_T^m - X_{t^*}^n}{\delta} \right) \mathcal{Y}_T^m} \times \mathbf{1}_{\frac{1}{NM} \delta^{-d} \sum_{n=1}^N \sum_{m=1}^M K \left(\frac{Y_T^m - X_{t^*}^n}{\delta} \right) \mathcal{Y}_T^m > \bar{p}/2}$$

- ▶ Estimator: for (X^n) i.i.d., (Y^m, \mathcal{Y}^m) i.i.d.,

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$$\times \mathbf{1}_{\frac{1}{NM} \delta^{-d} \sum_{n=1}^N \sum_{m=1}^M K\left(\frac{Y_T^m - X_{t^*}^n}{\delta}\right) \mathcal{Y}_T^m > \bar{p}/2},$$

- ▶ Assume **exact** simulation of X, Y, \mathcal{Y} .

Theorem

Assume $p(s_0, x, T, y) > \bar{p} > 0$, choose $M = N$. Then the mean squared error of the forward-reverse estimator is of order

$$\text{MSE} = O\left(\delta^{2(r+1)} + \frac{1}{N} + \frac{1}{N^2 \delta^d}\right).$$

$$\frac{1}{NM} \sum_{n=1}^N \sum_{m=1}^M K_{\delta} (Y_T^m - X_{t^*}^n) \mathcal{Y}_T^m$$

- ▶ Assume that kernel K (essentially) has support with diameter r
- ▶ Order points $X^n(t^*)$, $Y^m(T)$, $n, m = 1, \dots, N$, into boxes with side length δr (Cost: $O(N \log N)$)
- ▶ Fix $X^n(t^*)$; contribution only from $Y^m(T)$ in the same or neighboring boxes
- ▶ Number of such $Y^m(T)$ is $O(\delta^d N)$ on average.
- ▶ For $\delta = O(N^{-1/d})$, average total cost: $O(N \log(N)^2)$

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- ▶ For $\delta = O(N^{-1/d})$, average total cost: $O(N \log(N)^2)$

- ▶ Assume that $X_{s_0,x}(s), (Y_{t^*,y}(t), \mathcal{Y}_{t^*,y}(T))$ can be simulated **exactly** at **constant** cost.
- ▶ Cost of simulation step: $O(N)$
- ▶ Cost of “box-ordering” step: $O(N \log(N))$
- ▶ Cost of evaluation step: $O(\max(N^2 \delta^d, N) \log(N)^2)$

Cost estimate

- ▶ Assume that $X_{s_0,x}(s), (Y_{t^*,y}(t), \mathcal{Y}_{t^*,y}(T))$ can be simulated exactly at constant cost.
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- ▶ Cost of evaluation step: $O(\max(N^2 \delta^d, N) \log(N)^2)$

Cost estimate

- ▶ Case $d \leq 2(r+1)$: Choose $N = \epsilon^{-2}$, $\delta = \epsilon^{2/d}$, achieve MSE $O(\epsilon^2)$ at average cost $O(\epsilon^{-2} \log(\epsilon^{-1})^2)$
- ▶ Case $d > 2(r+1)$: Choose $N = \epsilon^{-(1+\frac{d}{2(r+1)})}$, $\delta = \epsilon^{1/(r+1)}$, achieve MSE $O(\epsilon^2)$ at average cost $O(\epsilon^{-(1+\frac{d}{2(r+1)})} \log(\epsilon^{-1})^2)$
- ▶ Curse of dimensionality for $d > 2(r+1)$

- ▶ Assume that $X_{s_0,x}(s), (Y_{t^*,y}(t), \mathcal{Y}_{t^*,y}(T))$ can be simulated exactly at constant cost.
- ▶ Cost of simulation step: $O(N)$
- ▶ Cost of “box-ordering” step: $O(N \log(N))$
- ▶ Cost of evaluation step: $O(\max(N^2 \delta^d, N) \log(N)^2)$

Cost estimate

- ▶ Case $d \leq 2(r+1)$: Choose $N = \epsilon^{-2}$, $\delta = \epsilon^{2/d}$, achieve MSE $O(\epsilon^2)$ at average cost $O(\epsilon^{-2} \log(\epsilon^{-1})^2)$
- ▶ Case $d > 2(r+1)$: Choose $N = \epsilon^{-(1+\frac{d}{2(r+1)})}$, $\delta = \epsilon^{1/(r+1)}$, achieve MSE $O(\epsilon^2)$ at average cost $O(\epsilon^{-(1+\frac{d}{2(r+1)})} \log(\epsilon^{-1})^2)$
- ▶ Curse of dimensionality for $d > 2(r+1)$

- ▶ Replace exact values $X_{s_0,x}(s)$, $(Y_{t^*,y}(t), \mathcal{Y}_{t^*,y}(T))$ by approximated values obtained from Euler discretization
- ▶ Use Euler steps of size h

Single level complexity estimate

- ▶ Case $d \leq 2(r+1)$: Choose $N = \epsilon^{-2}$, $\delta = \epsilon^{2/d}$, $h = \epsilon$, achieve MSE $O(\epsilon^2)$ at average cost $O(\epsilon^{-(2+1)} \log^2 \epsilon^{-1})$
- ▶ Case $d > 2(r+1)$: Choose $N = \epsilon^{-(1+\frac{d}{2(r+1)})}$, $\delta = \epsilon^{1/(r+1)}$, $h = \epsilon$, achieve MSE $O(\epsilon^2)$ at average cost $O(\epsilon^{-(1+\frac{d}{2(r+1)}+1)} \log^2 \epsilon^{-1})$

- ▶ Single level estimator for numerator (for $N = M$):

$$\frac{1}{N^2} \sum_{n,m=1}^N g_{n,m}^{(h)} K_{\delta} \left(Y_{T,m}^{(h)} - X_{t^*,n}^{(h)} \right) \mathcal{Y}_{T,m}^{(h)}$$

$$\frac{1}{N_0^2} \sum_{n,m=1}^{N_0} g_{n,m}^{(h_0)} K_\delta \left(Y_{T,m}^{(h_0)} - X_{t^*,n}^{(h_0)} \right) \mathcal{Y}_{T,m}^{(h_0)} +$$

$$\sum_{l=1}^L \frac{1}{N_l^2} \sum_{n,m=1}^{N_l} \left(g_{n,m}^{(h_l)} K_\delta \left(Y_{T,m}^{(h_l)} - X_{t^*,n}^{(h_l)} \right) \mathcal{Y}_{T,m}^{(h_l)} - g_{n,m}^{(h_{l-1})} K_\delta \left(Y_{T,m}^{(h_{l-1})} - X_{t^*,n}^{(h_{l-1})} \right) \mathcal{Y}_{T,m}^{(h_{l-1})} \right)$$

$$\frac{1}{N_0^2} \sum_{n,m=1}^{N_0} g_{n,m}^{(h_0)} K_\delta \left(Y_{T,m}^{(h_0)} - X_{t^*,n}^{(h_0)} \right) \mathcal{Y}_{T,m}^{(h_0)} +$$

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Some complexity results (ignoring log-terms)

- ▶ Euler scheme, $8 < d \leq 2(r+1)$: complexity $\mathcal{O}\left(\epsilon^{-(2+\frac{4}{d-2}+1/3)}\right)$
- ▶ Milstein scheme, $8 < d \leq 2(r+1)$: complexity $\mathcal{O}\left(\epsilon^{-(2+\frac{4}{d-2})}\right)$

Further possible multilevel strategies

- ▶ Use smaller δ on higher levels: $\delta \rightarrow \delta_l$
- ▶ Use higher order kernel K on higher levels: $K_\delta \rightarrow K_\delta^l$ or $K_\delta \rightarrow K_{\delta_l}^l$
- ▶ Include "cross-terms": $g_{n,m}^{(h_l)} K_\delta \left(Y_{T,m}^{(h_l)} - X_{t^*,n}^{(h_l)} \right) \mathcal{Y}_{T,m}^{(h_l)}$

$$\frac{1}{N_0^2} \sum_{n,m=1}^{N_0} g_{n,m}^{(h_0)} K_\delta \left(Y_{T,m}^{(h_0)} - X_{t^*,n}^{(h_0)} \right) \mathcal{Y}_{T,m}^{(h_0)} +$$

$$\sum_{l=1}^L \frac{1}{N_l^2} \sum_{n,m=1}^{N_l} \left(g_{n,m}^{(h_l)} K_\delta \left(Y_{T,m}^{(h_l)} - X_{t^*,n}^{(h_l)} \right) \mathcal{Y}_{T,m}^{(h_l)} - g_{n,m}^{(h_{l-1})} K_\delta \left(Y_{T,m}^{(h_{l-1})} - X_{t^*,n}^{(h_{l-1})} \right) \mathcal{Y}_{T,m}^{(h_{l-1})} \right)$$

Some complexity results (ignoring log-terms)

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Further possible multilevel strategies

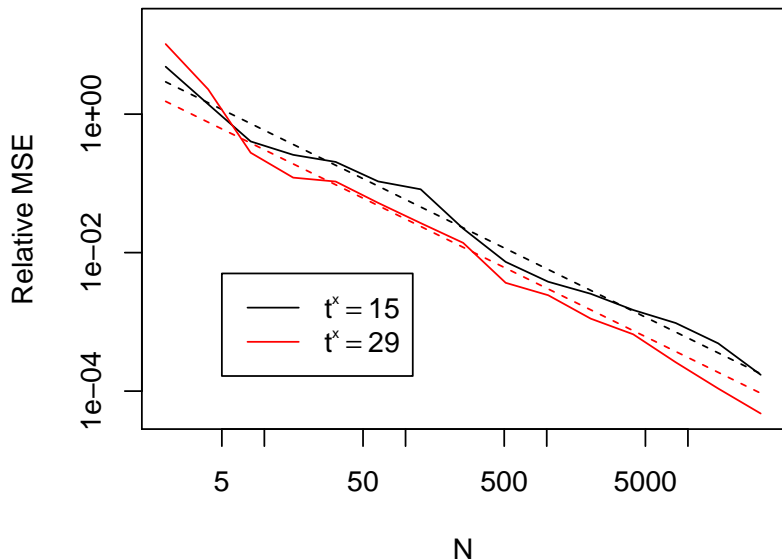
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- ▶ Use higher order kernel K on higher levels: $K_\delta \rightarrow K_\delta^l$ or $K_\delta \rightarrow K_{\delta_l}^l$
- ▶ Include “cross-terms”: $g_{n,m}^{(h_{l,k})} K_\delta \left(Y_{T,m}^{(h_l)} - X_{t^*,n}^{(h_k)} \right) \mathcal{Y}_{T,m}^{(h_l)}$

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- ▶ Heston model:

$$dS_t = \mu S_t dt + \sqrt{v_t} S_t dB_t^1,$$
$$dv_t = (\alpha v_t + \beta) dt + \xi \sqrt{v_t} \left(\rho dB_t^1 + \sqrt{1 - \rho^2} dB_t^2 \right)$$

- ▶ $a(x) = \begin{pmatrix} \mu x_1 \\ \alpha x_2 + \beta \end{pmatrix}$, $\sigma(x) = \begin{pmatrix} x_1 \sqrt{x_2} & 0 \\ \xi \rho \sqrt{x_2} & \xi \sqrt{1 - \rho^2} \sqrt{x_2} \end{pmatrix}$
- ▶ Reverse drift: $\alpha(x) = \begin{pmatrix} (2x_2 + \rho\xi - \mu)x_1 \\ (\rho\xi - \alpha)x_2 + \xi^2 - \beta \end{pmatrix}$, $c(x) = x_2 + \rho\xi - \mu - \alpha$.
- ▶ Realized variance: $RV := \sum_{i=1}^{30} (\log(S_{t_{i+1}}) - \log(S_{t_i}))^2$
- ▶ Objective: $\mathbb{E}[RV | S_T = s]$, $T = 1/12$



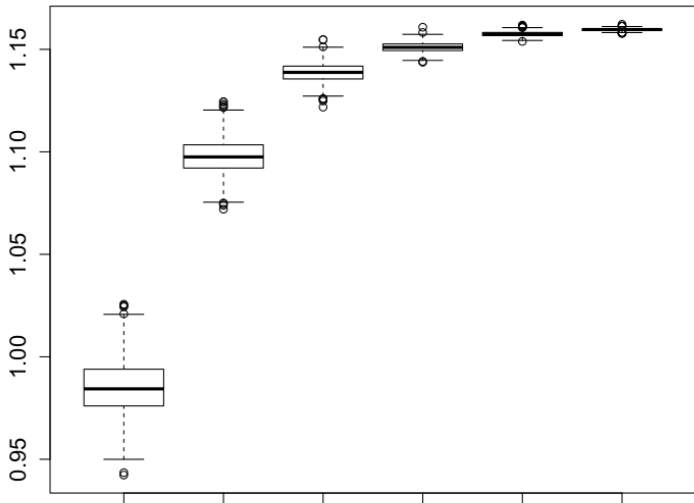
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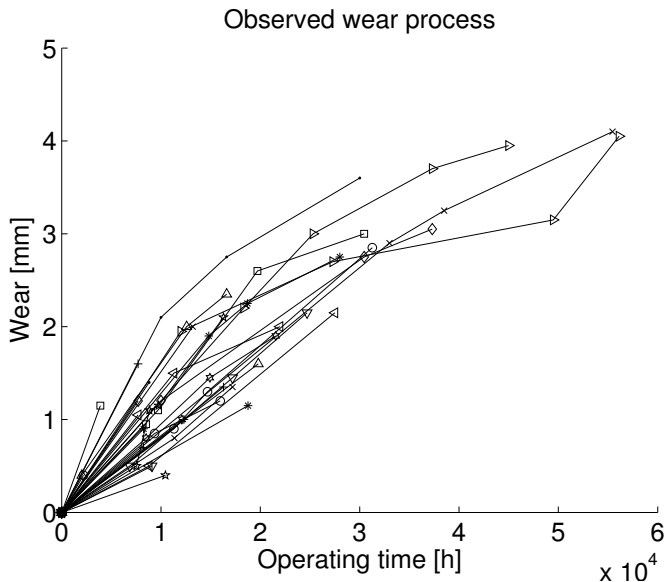
- ▶ X a suitable diffusion (or more general Markov) process observed at discrete times s_0, \dots, s_K
- ▶ Given data $\mathbf{x} = (X(s_0), \dots, X(s_K))$, unknown parameter θ
- ▶ Log-likelihood function on paths-space
$$g = g(X; \theta) = g((X(t))_{s_0 \leq t \leq s_K}; \theta)$$

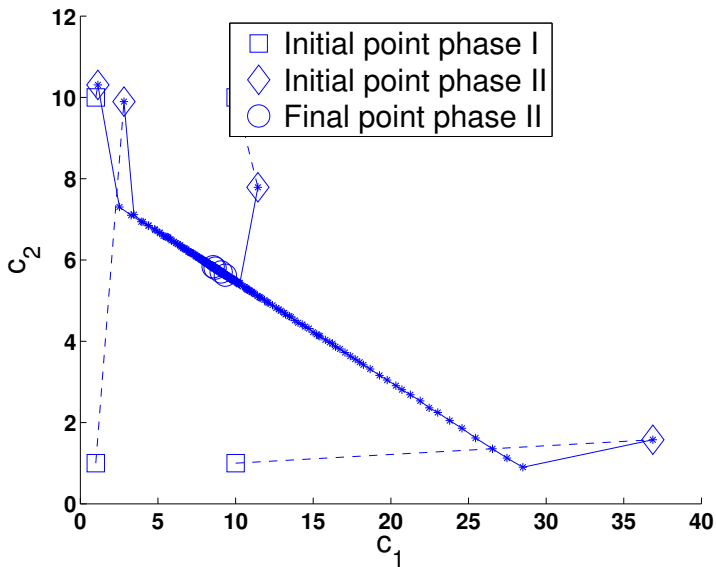
EM algorithm







(E) $Q(\theta|\theta_n, \mathbf{x}) := E_{\theta_n} [g(X; \theta) | (X(s_0), \dots, X(s_K)) = \mathbf{x}]$

(M) $\theta_{n+1} := \arg \max_{\theta \in \Theta} Q(\theta|\theta_n, \mathbf{x})$.







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