

# Hierarchical low-rank approximation for high dimensional approximation

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Supported by the ANR (CHORUS project)

- Parameter-dependent models

$$u : \Xi \rightarrow X \quad \text{such that} \quad \mathcal{F}(u(\xi); \xi) = 0$$

where  $\xi$  are random variables taking values in a measure space  $(\Xi, \mu)$ .

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- **Inverse problem:** Given observations of  $s(\xi)$ , estimate  $\mu$ .

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Compute an accurate approximation of  $u(\xi)$  or  $s(\xi)$  (metamodel, surrogate, reduced order model...) which allows fast evaluations of output variables of interest or observables.

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- **Complexity issues:**

- Complex numerical models:

$$u(\xi) \in X, \quad \dim(X) = n \gg 1$$

- Approximation of high-dimensional functions:

$$s(\xi_1, \dots, \xi_d), \quad d \gg 1$$

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- “Naive” tensor product discretization yields high-dimensional parametrizations

$$u(x_1, \dots, x_d) \approx \sum_{\alpha_1=1}^n \dots \sum_{\alpha_d=1}^n a_{\alpha_1 \dots \alpha_d} \psi_{\alpha_1}^{(1)}(x_1) \dots \psi_{\alpha_d}^{(d)}(x_d), \quad a \in \mathbb{R}^{n^d}$$



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- Assuming  $u \in C^s((0, 1)^d)$ , accuracy

$$\epsilon = O(n^{-s}) = O(N^{-s/d})$$

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- Extra smoothness does not help

## Remedies: structured approximations

Specific structures of the function have to be exploited in order to break down the complexity (application dependent)

- Low effective dimensionality,

$$u(x_1, \dots, x_d) \approx u_1(x_1),$$

- Low-order interactions,

$$u(x_1, \dots, x_d) \approx u_0 + \sum_i u_i(x_i)$$

- Sparsity (relatively to a basis or frame)

$$u(x) = \sum_{\alpha \in \mathbb{N}^d} u_\alpha \psi_\alpha(x) \approx \sum_{\alpha \in \Lambda} u_\alpha \psi_\alpha(x)$$

- ...
- Low-rank structures

- 1 Rank-structured approximation
- 2 Statistical learning methods for tensor approximation
- 3 Adaptive approximation in tree-based low-rank formats

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# Rank-structured approximation

- Multivariate function  $u(x_1, \dots, x_d)$  identified with an element of the tensor space

$$V_1 \otimes \dots \otimes V_d = \overline{\text{span}}\{v^1(x_1) \dots v^d(x_d); v^\mu \in V_\mu\}$$

- Approximation in a subset of tensors with bounded rank

$$\mathcal{M}_{\leq r} = \{v \in V_1 \otimes \dots \otimes V_d; \text{rank}(v) \leq r\}$$

- For order-two tensors, a single notion of rank:

$$\text{rank}(v) \leq r \iff v = \sum_{i=1}^r v_i^1(x_1) v_i^2(x_2)$$

- For higher-order tensors, different notions of rank, such as the **canonical rank**

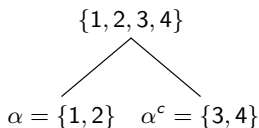
$$\text{rank}(v) \leq r \iff v = \sum_{i=1}^r v_i^1(x_1) \dots v_i^d(x_d)$$

Storage complexity:  $O(rdn)$

# Subspace based low-rank formats

- $\alpha$ -rank: for  $\alpha \subset \{1, \dots, d\}$ ,  $V = V_\alpha \otimes V_{\alpha^c}$ , with  $V_\alpha = \bigotimes_{\mu \in \alpha} V_\mu$ , and

$$\begin{aligned} \text{rank}_\alpha(v) \leq r_\alpha &\iff v = \sum_{i=1}^{r_\alpha} v_i^\alpha(x_\alpha) v_i^{\alpha^c}(x_{\alpha^c}), \quad v_i^\alpha \in V_\alpha, \quad v_i^{\alpha^c} \in V_{\alpha^c} \\ &\iff v \in U_\alpha \otimes V_{\alpha^c} \quad \text{with} \quad \dim(U_\alpha) = r_\alpha \end{aligned}$$

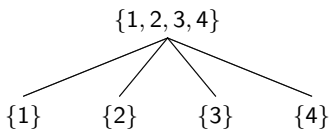


Storage complexity:  $O(r_\alpha(n^{\#\alpha} + n^{\#\alpha^c}))$



- Tucker rank:

$$\text{rank}_T(v) = (\text{rank}_1(v), \dots, \text{rank}_d(v))$$



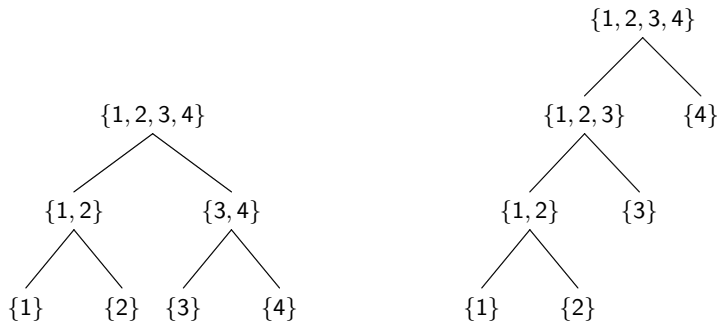
$$\begin{aligned} \text{rank}_T(v) \leq r = (r_1, \dots, r_d) &\iff v = \sum_{i_1=1}^{r_1} \dots \sum_{i_d=1}^{r_d} a_{i_1 \dots i_d} v_{i_1}^1 \otimes \dots \otimes v_{i_d}^d \\ &\iff v \in U_1 \otimes \dots \otimes U_d \quad \text{with} \quad \dim(U_\mu) = r_\mu \end{aligned}$$

storage complexity:  $O(dnR + R^d)$  with  $R \geq r_\mu$

## Subspace based low-rank formats

- Tree-based Tucker rank  [Hackbusch-Kuhn'09, Oseledets-Tyrtyshnikov'09]:


$$\text{rank}_T(v) = (\text{rank}_\alpha(v) : \alpha \in T) \quad \text{with } T \text{ a dimension tree}$$





storage complexity:  $O(dnR + dR^{s+1})$  with  $R \geq r_\mu$

**Example (additive model):**  $u(x_1, \dots, x_d) = u_1(x_1) + \dots + u_d(x_d)$  has  $\text{rank}_T(u) = (2, 2, \dots, 2)$  for any tree  $T$ .

## Subspace based low-rank formats

- **Storage and computational complexity** scales as  $O(d)$ .
- **Best approximation problems in  $\mathcal{M}_{\leq r} = \{v : \text{rank}_{\mathcal{T}}(v) \leq r\}$  are well-posed**, under natural conditions on tensor norms (for reflexive Banach spaces). Follows from the fact that  $\text{rank}_{\mathcal{T}}(\cdot)$  is weakly l.s.c..  [Falco-Hackbusch-Nouy '15].
- For Hilbert spaces, **quasi-optimal approximations** with respect to the canonical norm can be obtained by **higher-order versions of the SVD**

$$\|u - u_r\| \leq \sqrt{2d} \min_{\text{rank}_{\mathcal{T}}(v) \leq r} \|u - v\|$$

- The subsets  $\mathcal{M}_{\leq r}$  are **analytic Banach manifolds and immersed submanifolds** under the same conditions on tensor norms  [Falco-Hackbusch-Nouy '15] (see  [Holtz-Rohwedder-Schneider '11, Uschmajew-Vandereycken '13] for Hilbert setting).
- **Multilinear parametrization** of subsets of low-rank tensors

$$\mathcal{M}_{\leq r} = \{v = F(p_1, \dots, p_L); p_k \in P_k, 1 \leq k \leq L\}$$

- 1 Rank-structured approximation
- 2 Statistical learning methods for tensor approximation**
- 3 Adaptive approximation in tree-based low-rank formats

# Statistical learning methods for tensor approximation

- Approximation of a function  $u(\xi) = u(\xi_1, \dots, \xi_d)$  from evaluations  $\{y_k = u(x^k)\}_{k=1}^K$  on a **training set**  $\{x^k\}_{k=1}^K$  (i.i.d. samples of  $\xi$ )

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- Approximation in **subsets of rank-structured functions**

$$\mathcal{M}_{\leq r} = \{v : \text{rank}(v) \leq r\}$$

by minimization of an **empirical risk**

$$\hat{\mathcal{R}}_K(v) = \frac{1}{K} \sum_{k=1}^K \ell(u(x^k), v(x^k))$$

where  $\ell$  is a certain **loss function**.

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where  $\ell$  is a certain **loss function**.

- Here, we consider for **least-squares regression**

$$\widehat{\mathcal{R}}_K(v) = \frac{1}{K} \sum_{k=1}^K (u(x^k) - v(x^k))^2 = \widehat{\mathbb{E}}_K((u(\xi) - v(\xi))^2)$$

but other loss functions could be used for different objectives than  $L^2$ -approximation (e.g. classification).

- Multilinear parametrization of tensor manifolds

$$\mathcal{M}_{\leq r} = \{v = F(p_1, \dots, p_L) : p_l \in \mathbb{R}^{m_l}, 1 \leq l \leq L\}$$

so that

$$\min_{v \in \mathcal{M}_{\leq r}} \widehat{\mathcal{R}}_K(v) = \min_{p_1, \dots, p_L} \widehat{\mathcal{R}}_K(F(p_1, \dots, p_L))$$



# Alternating minimization algorithm

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- Alternating minimization algorithm: Successive minimization problems

$$\min_{p_l \in \mathbb{R}^{m_l}} \widehat{\mathcal{R}}_K(\underbrace{F(p_1, \dots, p_l, \dots, p_d)}_{\Psi_l(\cdot)^T p_l})$$

which are standard linear approximation problems

$$\min_{p_l \in \mathbb{R}^{m_l}} \frac{1}{K} \sum_{k=1}^K \ell(u(x^k), \Psi_l(x^k)^T p_l)$$

- Regularization

$$\min_{p_1, \dots, p_L} \widehat{\mathcal{R}}_K(F(p_1, \dots, p_L)) + \sum_{l=1}^L \lambda_l \Omega_l(p_l)$$

with regularization functionals  $\Omega_l$  promoting

- sparsity (e.g.  $\Omega_l(p_l) = \|p_l\|_1$ ),
  - smoothness,
  - ...
- **Alternating minimization algorithm** requires the solution of successive standard regularized linear approximation problems

$$\min_{p_l} \frac{1}{K} \sum_{k=1}^K \ell(u(x^k), \Psi_l(x^k)^T p_l) + \lambda_l \Omega_l(p_l) \quad (*)$$

- For square-loss and  $\Omega_l(p_l) = \|p_l\|_1$ , (\*) is a LASSO problem.
- **Cross-validation methods** for the selection of regularization parameters  $\lambda_l$ .

- **Approximation in tensor-train (TT) format:**

$$\text{rank}_{\{1, \dots, k\}}(v) \leq r_k, \forall k \iff v(x_1, \dots, x_d) = \sum_{i_1=1}^{r_1} \dots \sum_{i_{d-1}=1}^{r_{d-1}} v_{1, i_1}^1(x_1) \dots v_{i_{d-1}, 1}^d(x_d)$$

- **Polynomial approximations**

$$v_{i_{k-1}, i_k}^k \in \mathbb{P}_q$$

- $v = F(p_1, \dots, p_d)$  with parameter  $p_k \in \mathbb{R}^{(q+1)r_k r_{k-1}}$  gathering the coefficients of functions of  $x_k$  on a polynomial basis.
- **Sparsity inducing regularization** and **cross-validation** (leave one out) for the automatic selection of polynomial basis functions. Use of standard least-squares in the selected basis.

## Illustration : Borehole function

The Borehole function models water flow through a borehole:

$$u(\xi) = \frac{2\pi T_u(H_u - H_l)}{\ln(r/r_w) \left(1 + \frac{2LT_u}{\ln(r/r_w)r_w^2 K_w} + \frac{T_u}{T_l}\right)}, \quad \xi = (r_w, r, T_u, H_u, T_l, H_l, L, K_w)$$

---

$r_w$	radius of borehole (m)	$N(\mu = 0.10, \sigma = 0.0161812)$
$r$	radius of influence (m)	$LN(\mu = 7.71, \sigma = 1.0056)$
$T_u$	transmissivity of upper aquifer (m <sup>2</sup> /yr)	$U(63070, 115600)$
$H_u$	potentiometric head of upper aquifer (m)	$U(990, 1110)$
$T_l$	transmissivity of lower aquifer (m <sup>2</sup> /yr)	$U(63.1, 116)$
$H_l$	potentiometric head of lower aquifer (m)	$U(700, 820)$
$L$	length of borehole (m)	$U(1120, 1680)$
$K_w$	hydraulic conductivity of borehole (m/yr)	$U(9855, 12045)$

---

- Polynomial approximation with degree  $q = 8$ .
- Test set of size 1000.

## Illustration : Borehole function

- Test error for different ranks and for different sizes  $K$  of the training set.

rank	$K = 100$	$K=1000$	$K=10000$
(1 1 1 1 1 1 1)	$1.7 \cdot 10^{-2}$	$1.4 \cdot 10^{-2}$	$1.4 \cdot 10^{-2}$
(2 2 2 2 2 2 2)	$6.7 \cdot 10^{-4}$	$9.1 \cdot 10^{-4}$	$3.3 \cdot 10^{-4}$
(3 3 3 3 3 3 3)	$3.2 \cdot 10^{-3}$	$1.2 \cdot 10^{-4}$	$1.0 \cdot 10^{-5}$
(4 4 4 4 4 4 4)	$2.1 \cdot 10^{-1}$	$7.6 \cdot 10^{-5}$	$1.9 \cdot 10^{-7}$
(5 5 5 5 5 5 5)	$7.3 \cdot 10^0$	$3.8 \cdot 10^{-4}$	$2.8 \cdot 10^{-7}$
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- Finding optimal rank is a combinatorial problem...

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- 2 Statistical learning methods for tensor approximation
- 3 Adaptive approximation in tree-based low-rank formats

## Heuristic strategy for rank adaptation (tree-based Tucker format)

- Given  $T \subset 2^{\{1, \dots, d\}}$ , construction of a sequence of approximations  $u_m$  in tree-based Tucker format with increasing rank:

$$u_m \in \{v : \text{rank}_T(v) \leq (r_\alpha^m)_{\alpha \in T}\}$$



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- At iteration  $m$ ,

$$\begin{cases} r_\alpha^{m+1} = r_\alpha^m + 1 & \text{if } \alpha \in T_m \\ r_\alpha^{m+1} = r_\alpha^m & \text{if } \alpha \notin T_m \end{cases}$$

where  $T_m$  is selected in order to obtain (hopefully) the fastest decrease of the error.

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where  $T_m$  is selected in order to obtain (hopefully) the fastest decrease of the error.

- A possible strategy consists in computing the singular values

$$\sigma_1^\alpha \geq \dots \geq \sigma_{r_\alpha^m}^\alpha$$

of  $\alpha$ -matricizations  $\mathcal{M}_\alpha(u_m)$  of  $u_m$  for all  $\alpha \in T$ ,

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- $\sigma_{r_\alpha^m}^\alpha$  provides an estimation of an upper bound of  $\|u - u_m\|_{V(V_\alpha \otimes V_{\alpha^c})}$

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- $\sigma_{r_\alpha^m}^\alpha$  provides an estimation of an upper bound of  $\|u - u_m\|_{V(V_\alpha \otimes V_{\alpha^c})}$
- Letting  $0 \leq \theta \leq 1$ , we choose

$$T_m = \left\{ \alpha \in T : \sigma_{r_\alpha^m}^\alpha \geq \theta \max_{\beta \in T} \sigma_{r_\beta^m}^\beta \right\}$$

## Illustration : Borehole function

- Training set of size  $K = 1000$

iteration	rank	test error
0	(1 1 1 1 1 1 1)	$1.4 \cdot 10^{-2}$
1	(2 2 2 2 2 2 2)	$4.4 \cdot 10^{-4}$
2	(2 2 2 3 3 2 2)	$8.1 \cdot 10^{-6}$
3	(3 3 3 4 3 2 2)	$6.2 \cdot 10^{-6}$
4	(3 3 3 4 4 3 2)	$2.1 \cdot 10^{-5}$
5	(3 3 3 4 4 3 3)	$9.6 \cdot 10^{-6}$
6	(3 4 4 4 5 4 4)	$1.5 \cdot 10^{-5}$

The selected rank is one order of magnitude better than the optimal “isotropic” rank  $(r, r, \dots, r)$

## Illustration : Borehole function

- Different sizes  $K$  of training set, selection of optimal ranks.

### TT format

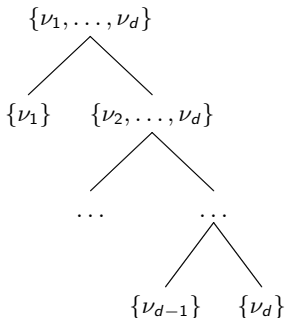
K	rank	test error
100	(3 3 3 4 3 2 2)	$8.4 \cdot 10^{-4}$
1000	(3 3 3 4 4 3 2)	$6.2 \cdot 10^{-6}$
10000	(5 6 6 7 7 5 4)	$2.4 \cdot 10^{-8}$

### Canonical format

K	rank	test error
100	3	$6.1 \cdot 10^{-4}$
1000	5	$3.8 \cdot 10^{-4}$
10000	7	$6.0 \cdot 10^{-6}$

# Influence of the tree

- Test error for different trees  $T$  (Training set of size  $K = 100$ )



tree	$\{\nu_1, \dots, \nu_d\}$	optimal rank	test error
$T_1$	(1 2 3 4 5 6 7 8)	(2 2 2 3 3 2 2)	$1.1 \cdot 10^{-4}$
$T_2$	(7 6 8 1 4 5 2 3)	(1 1 1 1 1 1 1)	$1.4 \cdot 10^{-2}$
$T_3$	(8 2 4 7 5 1 3 6)	(3 3 4 3 3 3 3)	$1.4 \cdot 10^{-3}$

Finding the optimal tree is a combinatorial problem...

- Need for robust strategies for tree adaptation.
- For rank adaptation, possible use of constructive (greedy) algorithms for tree-based Tucker formats.
- “Statistical dimension” of low-rank subsets ?
- Adaptive sampling strategies.
- Goal-oriented construction of low-rank approximations.





A. Nouy.

Low-rank methods for high-dimensional approximation and model order reduction.  
arXiv:1511.01554



M. Chevreuril, R. Lebrun, A. Nouy, and P. Rai.

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